# Homotopy techniques for analytic combinatorics in several variables 

(joint work with Stephen Melczer ${ }^{\dagger}$ and Josip Smolčić ${ }^{\dagger}$ )
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## Acknowledgements

MATHEMATICS
RESEARCH COMMUNITIES

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Combinatorial Applications of Computational Geometry and Algebraic Topology


## Analytic combinatorics

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$F(z)=\sum_{i=1}^{\infty} f_{i} z^{i}$ : the generating function of the
sequence.

- The generating function can be considered as the power series expansion of a complex valued function.
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- (Cauchy integral formula). $f_{n}=\frac{1}{2 \pi i} \int_{\gamma} F(z) \frac{d z}{z^{n+1}}$
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(Need a system of equations)

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- Define Abs : $\left(z_{1}, \ldots, z_{n}\right) \mapsto\left|z_{1} \cdots z_{n}\right|$.
- We are interested in critical points of Abs.
- $\mathscr{V}:=\left\{\mathbf{z} \in \mathbb{C}^{n} \mid H(\mathbf{z})=0\right\}$ : the singular variety of $F=\frac{G}{H}$
- The critical points for Abs on $\mathscr{V}$ are obtained by solving a polynomial system
. $H(\mathbf{z})=0, \quad z_{1} \frac{\partial H}{\partial z_{1}}=\cdots=z_{n} \frac{\partial H}{\partial z_{n}}$ (critical-point equations)
- We assume that all critical points are smooth.
- Especially, we are interested in minimal critical points
(i.e. critical points lie in $\partial \mathscr{D} \cap \mathscr{V}$ ).


## ACSV + Numerical algebraic geometry (how to construct a system of equations)

- $F(\mathbf{z})=\frac{G(\mathbf{z})}{H(\mathbf{z})}$ where $G$ and $H$ are co-prime polynomials with $H(\mathbf{0}) \neq 0$.
. $F(\mathbf{z})=\sum_{\mathbf{i} \in \mathbb{N}^{n}} f_{\mathbf{i}} \mathbf{z}^{\mathbf{i}}$ : The Taylor expansion of $F$ centered at the origin with a nonempty open domain of convergence $\mathscr{D} \subset \mathbb{C}^{n}$.
- Interested in computing the asymptotic behavior of coefficients of $\left(f_{\mathbf{i}}\right)_{\mathbf{i}}$.

$$
f_{i_{1}, \ldots, i_{n}}=\frac{1}{(2 \pi i)^{n}} \int_{\gamma} \frac{F(\mathbf{z})}{z_{1}^{i_{1} \cdots z_{n}^{i_{n}}}} \cdot \frac{d z_{1} \cdots d z_{n}}{z_{1} \cdots z_{n}}
$$

- It is important to find where the singularity locates.
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## ACSV for combinatorial case (Melczer-Salvy 2021)

$F(\mathbf{z})=\sum_{\mathbf{i} \in \mathbb{N}^{n}} f_{\mathbf{i}} \mathbf{z}^{\mathbf{i}}$ is called combinatorial if all coefficients
$f_{\mathbf{i}}$ of the Taylor expansion are non-negative.


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1. Determine the set $\mathcal{S}$ of zeros $(\mathbf{z}, \lambda, t)$ of the system $\left[H, z_{1} \frac{\partial H}{\partial z_{1}}-\lambda, \ldots, z_{n} \frac{\partial H}{\partial z_{n}}-\lambda, H\left(t z_{1}, \ldots, t z_{n}\right)\right]$. If $\mathcal{S}$ is not finite, then FAIL.
2. Construct the subset points $(\zeta, \lambda, t) \in \mathcal{S}$ which are
candidates for minimal critical points.

- $\mathbf{Z}$ is minimal if and only if the line segment
$\left\{\left(t\left|z_{1}\right|, \ldots, t\left|z_{n}\right|\right) \mid 0<t<1\right\}$ doesn't intersect $\mathscr{V}$

3. Identify $\zeta$ among the elements of $\mathscr{C}$ (critical points Abs on
4. Return
$\mathscr{U}:=\left\{\mathbf{z} \in \mathbb{C}^{n}| | z_{1}\left|=\left|\zeta_{1}\right|, \ldots,\left|z_{n}\right|=\left|\zeta_{n}\right|\right.\right.$ for some $\left.(\mathbf{z}, \lambda) \in \mathscr{C}\right\}$

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$$
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$$

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1. Determine the set $\mathcal{S}$ of zeros $(\mathbf{z}, \lambda, t)$ of the system $\left[H, \frac{\partial H}{} \frac{\partial H}{\partial z_{1}}-\lambda, \ldots, z_{n} \frac{\partial H}{\partial z_{n}}-\lambda, H\left(t z_{1}, \ldots, t z_{n}\right)\right]$. If $\mathcal{S}$ is not finite, then FAlL.
2. Construct the subset points $(\zeta, \lambda, t) \in \mathcal{S}$ which are candidates for minimal critical points.

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$$
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$-\mathbf{z}$ is minimal if and only if the line segment
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## Doesn't hold if $F$ is not combinatorial

3. Identify $\zeta$ among the elements of $\mathscr{C}$ (critical points Abs on $\mathscr{V}$ ).
4. Return
$\mathscr{U}:=\left\{\mathbf{z} \in \mathbb{C}^{n}| | z_{1}\left|=\left|\zeta_{1}\right|, \ldots,\left|z_{n}\right|=\left|\zeta_{n}\right|\right.\right.$ for some $\left.(\mathbf{z}, \lambda) \in \mathscr{C}\right\}$

## ACSV for non-combinatorial case (Melczer-Salvy 2021)

Q. How to deal with non-combinatorial case?
equations are given as

Lemma (Melczer-Salvy 2021)
$H^{(R)}(\mathbf{a}, \mathbf{b})=H^{(I)}(\mathrm{a}, \mathrm{b})=0$

Let $D(\mathbb{z}):=\left\{\mathbf{w} \in \mathbb{C}^{n}| | w_{i}\left|<\left|z_{i}\right|, i=1, \ldots, n\right\}\right.$ be
$\mathbf{z} \in \partial \mathscr{D}$
Q. How to deal with polydisk using polynomial equations?
A. Decompose polynomials into the real and imaginary

Want to have no solutions with $\mathbf{x}, \mathbf{y}, t$ real and $0<t<1$
For checking extremity for values of $t$, we add equations

For derivatives, applying Cauchy-Riemann equations,


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Using real and imaginary part decomposition, critical-point
Q. How to deal with non-combinatorial case?

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Let $D(\mathbf{z}):=\left\{\mathbf{w} \in \mathbb{C}^{n}| | w_{i}\left|<\left|z_{i}\right|, i=1, \ldots, n\right\}\right.$ be the open polydisk. If $\mathbf{z} \in \mathscr{V}$ and $\mathscr{V} \cap D(\mathbf{z})=\varnothing$, then $\mathbf{z} \in \partial \mathscr{D}$.
Q. How to deal with polydisk using polynomial equations?
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For derivatives, appluina Cauchu-Riemann equations
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For checking emptiness of $\mathscr{V} \cap D(\mathbf{z})=\varnothing$, we consider
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A. Decompose polynomials into the real and imaginary part.

Using real and imaginary part decomposition, critical-point
equations are given as

2. For checking emptiness of $\mathscr{V} \cap D(\mathbf{z})=\varnothing$, we consider equations

$$
H^{(R)}(\mathrm{x}, \mathrm{y})=H^{(T)}(\mathrm{x}, \mathrm{y})=0
$$

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H^{(R)}(\mathbf{a}, \mathbf{b})=H^{(I)}(\mathbf{a}, \mathbf{b})=0
$$

$a_{j} \frac{\partial H^{(R)}}{\partial x_{j}}(\mathbf{a}, \mathbf{b})+b_{j} \frac{\partial H^{(R)}}{\partial y_{j}}(\mathbf{a}, \mathbf{b})-\lambda_{R}=0$

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f(\mathbf{x}+i \mathbf{y})=f^{(R)}(\mathbf{x}, \mathbf{y})+i f^{(I)}(\mathbf{x}, \mathbf{y})
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For derivatives, applying Cauchy-Riemann equations,

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$$

For derivatives, applying Cauchy-Riemann equations,
$\frac{\partial f}{\partial z_{j}}(\mathbf{x}+i \mathbf{y})=\frac{1}{2} \cdot \frac{\partial}{\partial x_{j}}\left(f^{(R)}(\mathbf{x}, \mathbf{y})+i f^{(t)}(\mathbf{x}, \mathbf{y})\right)-\frac{i}{2} \cdot \frac{\partial}{\partial y_{j}}\left(f^{(R)}(\mathbf{x}, \mathbf{y})+i f^{(t)}(\mathbf{x}, \mathbf{y})\right)$

Using real and imaginary part decomposition, critical-point
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1. Using real and imaginary part decomposition, critical-point equations are given as

$$
\begin{array}{rl}
H^{(R)}(\mathbf{a}, \mathbf{b})=H^{(I)}(\mathbf{a}, \mathbf{b})=0 \\
a_{j} \frac{\partial H^{(R)}}{\partial x_{j}}(\mathbf{a}, \mathbf{b})+b_{j} \frac{\partial H^{(R)}}{\partial y_{j}}(\mathbf{a}, \mathbf{b})-\lambda_{R}=0 & j=1, \ldots, n \\
a_{j} \frac{\partial H^{(I)}}{\partial x_{j}}(\mathbf{a}, \mathbf{b})+b_{j} \frac{\partial H^{(I)}}{\partial y_{j}}(\mathbf{a}, \mathbf{b})-\lambda_{I}=0 & j=1, \ldots, n
\end{array}
$$

2. For checking emptiness of $\mathscr{V} \cap D(\mathbb{z})=\varnothing$, we consider equations

$$
H^{(R)}(\mathrm{x}, \mathrm{y})=H^{(I)}(\mathrm{x}, \mathrm{y})=0
$$

Want to have no solutions with $\mathbf{x}, \mathbf{y}, t$ real and $0<t<1$.
3. For checking extremity for values of $t$, we add equations


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Q. How to deal with polydisk using polynomial equations?
A. Decompose polynomials into the real and imaginary part.

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f(\mathbf{x}+i \mathbf{y})=f^{(R)}(\mathbf{x}, \mathbf{y})+i f^{(I)}(\mathbf{x}, \mathbf{y})
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For derivatives, applying Cauchy-Riemann equations,
$\frac{\partial f}{\partial z_{j}}(\mathbf{x}+i \mathbf{y})=\frac{1}{2} \cdot \frac{\partial}{\partial x_{j}}\left(f^{(R)}(\mathbf{x}, \mathbf{y})+i f^{(I)}(\mathbf{x}, \mathbf{y})\right)-\frac{i}{2} \cdot \frac{\partial}{\partial y_{j}}\left(f^{(R)}(\mathbf{x}, \mathbf{y})+i f^{(I)}(\mathbf{x}, \mathbf{y})\right)$

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a_{j} \frac{\partial H^{(I)}}{\partial x_{j}}(\mathbf{a}, \mathbf{b})+b_{j} \frac{\partial H^{(I)}}{\partial y_{j}}(\mathbf{a}, \mathbf{b})-\lambda_{I}=0 & j=1, \ldots, n
\end{array}
$$

2. For checking emptiness of $\mathscr{V} \cap D(\mathbf{z})=\varnothing$, we consider equations

$$
\begin{aligned}
H^{(R)}(\mathbf{x}, \mathbf{y})=H^{(I)}(\mathbf{x}, \mathbf{y}) & =0 \\
x_{j}^{2}+y_{j}^{2}-t\left(a_{j}^{2}+b_{j}^{2}\right) & =0 \quad j=1, \ldots, n
\end{aligned}
$$

Want to have no solutions with $\mathbf{x}, \mathbf{y}, t$ real and $0<t<1$.
3. For checking extremity for values of $t$, we add equations $\left(y_{j}-\nu x_{j}\right) \frac{\partial H^{(R)}}{\partial x_{j}}(\mathbf{x}, \mathbf{y})-\left(x_{j}+\nu y_{j}\right) \frac{\partial H^{(R)}}{\partial y_{j}}(\mathbf{x}, \mathbf{y})=0, \quad j=1, \ldots, n$ Want to have no solutions with $\mathbb{X}, \mathbb{y}, \nu, t$ real and $0<t<1$.

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Q. How to deal with polydisk using polynomial equations?
A. Decompose polynomials into the real and imaginary part.

$$
f(\mathbf{x}+i \mathbf{y})=f^{(R)}(\mathbf{x}, \mathbf{y})+i f^{(I)}(\mathbf{x}, \mathbf{y})
$$

For derivatives, applying Cauchy-Riemann equations,
$\frac{\partial f}{\partial z_{j}}(\mathbf{x}+i \mathbf{y})=\frac{1}{2} \cdot \frac{\partial}{\partial x_{j}}\left(f^{(R)}(\mathbf{x}, \mathbf{y})+i f^{(I)}(\mathbf{x}, \mathbf{y})\right)-\frac{i}{2} \cdot \frac{\partial}{\partial y_{j}}\left(f^{(R)}(\mathbf{x}, \mathbf{y})+i f^{(I)}(\mathbf{x}, \mathbf{y})\right)$

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& a_{j} \frac{\partial H^{(I)}}{\partial x_{j}}(\mathbf{a}, \mathbf{b})+b_{j} \frac{\partial H^{(I)}}{\partial y_{j}}(\mathbf{a}, \mathbf{b})-\lambda_{I}=0 \quad j=1, \ldots, n
\end{aligned}
$$

2. For checking emptiness of $\mathscr{V} \cap D(\mathbf{z})=\varnothing$, we consider equations

$$
\begin{aligned}
H^{(R)}(\mathbf{x}, \mathbf{y})=H^{(I)}(\mathbf{x}, \mathbf{y}) & =0 \\
x_{j}^{2}+y_{j}^{2}-t\left(a_{j}^{2}+b_{j}^{2}\right) & =0 \quad j=1, \ldots, n
\end{aligned}
$$

Want to have no solutions with $\mathbf{x}, \mathbf{y}, t$ real and $0<t<1$.
3. For checking extremity for values of $t$, we add equations

$$
\left(y_{j}-\nu x_{j}\right) \frac{\partial H^{(R)}}{\partial x_{j}}(\mathbf{x}, \mathbf{y})-\left(x_{j}+\nu y_{j}\right) \frac{\partial H^{(R)}}{\partial y_{j}}(\mathbf{x}, \mathbf{y})=0, \quad j=1, \ldots, n
$$

Want to have no solutions with $\mathbf{x}, \mathbf{y}, \nu, t$ real and $0<t<1$.

## ACSV for non-combinatorial case (Melczer-Salvy 2021)

$$
\left.\begin{array}{rrr}
H^{(R)}(\mathbf{a}, \mathbf{b})=H^{(I)}(\mathbf{a}, \mathbf{b})=0 & \\
a_{j} \frac{\partial H^{(R)}}{\partial x_{j}}(\mathbf{a}, \mathbf{b})+b_{j} \frac{\partial H^{(R)}}{\partial y_{j}}(\mathbf{a}, \mathbf{b})-\lambda_{R}=0 & j=1, \ldots, n \\
a_{j} \frac{\partial H^{(I)}}{\partial x_{j}}(\mathbf{a}, \mathbf{b})+b_{j} \frac{\partial H^{(I)}}{\partial y_{j}}(\mathbf{a}, \mathbf{b})-\lambda_{I}=0 & j=1, \ldots, n \\
H^{(R)}(\mathbf{x}, \mathbf{y})=H^{(I)}(\mathbf{x}, \mathbf{y})=0 & \\
x_{j}^{2}+y_{j}^{2}-t\left(a_{j}^{2}+b_{j}^{2}\right)=0 & j=1, \ldots, n \\
\left(y_{j}-\nu x_{j}\right) \frac{\partial H^{(R)}}{\partial x_{j}}(\mathbf{x}, \mathbf{y})-\left(x_{j}+\nu y_{j}\right) \frac{\partial H^{(R)}}{\partial y_{j}}(\mathbf{x}, \mathbf{y})=0 & j=1, \ldots, n
\end{array}\right\}
$$

$(\star)$ is a square polynomial system with $4 n+4$ variables $\left(\mathbf{a}, \mathbf{b}, \mathbf{x}, \mathbf{y}, \lambda_{R}, \lambda_{I}, \nu, t\right)$.

## ACSV for combinatorial case

1. Determine the set $\mathcal{S}$ of zeros ( $\mathbf{z}, \lambda, t)$ of the system $\left[H, z_{1} \frac{\partial H}{\partial z_{1}}-\lambda, \ldots, z_{n} \frac{\partial H}{\partial z_{n}}-\lambda, H\left(t z_{1}, \ldots, t z_{n}\right)\right]$. If $\mathcal{S}$ is not finite, then FAIL.
2. Construct the subset points $(\boldsymbol{\zeta}, \lambda, t) \in \mathcal{S}$ which are candidates for minimal critical points.

- $\mathbf{z}$ is minimal if and only if the line segment $\left\{\left(t\left|z_{1}\right|, \ldots, t\left|z_{n}\right|\right) \mid 0<t<1\right\}$ doesn't intersect $\mathscr{V}$.

3. Identify $\boldsymbol{\zeta}$ among the elements of $\mathscr{C}$ (critical points Abs on $\mathscr{V}$ ).
4. Return
$\mathscr{U}:=\left\{\mathbf{z} \in \mathbb{C}^{n}| | z_{1}\left|=\left|\zeta_{1}\right|, \ldots,\left|z_{n}\right|=\left|\zeta_{n}\right|\right.\right.$ for some $\left.(\mathbf{z}, \lambda) \in \mathscr{C}\right\}$

## ACSV for non-combinatorial case

Determine the set $\mathcal{S}$ of zeros
( $\mathbf{a}, \mathbf{b}, \mathbf{x}, \mathbf{y}, \lambda_{R}, \lambda_{r}, \nu, t$ ) of the system (*). If $\delta$ is not finite, then FAIL.

Construct the set of minimal critical points $\mathscr{U}:=\left\{\mathbf{a}+i \mathbf{b} \mid\left(\mathbf{a}, \mathbf{b}, \mathbf{x}, \mathbf{y}, \lambda_{R}, \lambda_{I}, \nu, t\right) \in \mathcal{S}_{\mathbb{R}}, t \notin(0,1)\right\} \subset \delta$
3. If $\mathscr{U}=\varnothing$ or $\lambda_{R}=\lambda_{I}=0$ or the elements of $\mathscr{U}$ do not all belong to the same torus, then FAIL
4. Identify elements of $\mathscr{U}$ from $\mathscr{C}$ and return them

## ACSV for combinatorial case

1. Determine the set $\mathcal{S}$ of zeros ( $\mathbf{z}, \lambda, t)$ of the system $\left[H, z_{1} \frac{\partial H}{\partial z_{1}}-\lambda, \ldots, z_{n} \frac{\partial H}{\partial z_{n}}-\lambda, H\left(t z_{1}, \ldots, t z_{n}\right)\right]$. If $\mathcal{S}$ is not finite, then FAIL.
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## ACSVHomotopy.jl (L.-Melczer-Smolčić 2022)

- Implemented using HomotopyContinuation.jl (Breiding-Timme 2018)
- Available at github.com/ACSVMath/ACSVHomotopy
- Competitive to other ACSV software for combinatorial cases.
- Solve the critical-point equations using the polyhedral homotopy
- The first software of ACSV for noncombinatorial cases.
- Solve the decomposed critical-point equations ( $\star$ ) using the polyhedral homotopy
- Provide faster heuristics including the monodromy method.


## Implementation details

The polyhedral homotopy is the default for solving critical point equations.

- Returns reliable results via interval arithmetic certification.
- Effective for combinatorial case compared to other software based on symbolic algorithm.
- May be slow for non-combinatorial.
- Faster heuristics used.


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## Implementation details

Heuristics for non-combinatorial case.

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\left.\begin{array}{rrr}
H^{(R)}(\mathbf{a}, \mathbf{b})=H^{(I)}(\mathbf{a}, \mathbf{b})=0 & \\
a_{j} \frac{\partial H^{(R)}}{\partial x_{j}}(\mathbf{a}, \mathbf{b})+b_{j} \frac{\partial H^{(R)}}{\partial y_{j}}(\mathbf{a}, \mathbf{b})-\lambda_{R}=0 & j=1, \ldots, n \\
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x_{j}^{2}+y_{j}^{2}-t\left(a_{j}^{2}+b_{j}^{2}\right)=0 & j=1, \ldots, n \\
\left(y_{j}-\nu x_{j}\right) \frac{\partial H^{(R)}}{\partial x_{j}}(\mathbf{x}, \mathbf{y})-\left(x_{j}+\nu y_{j}\right) \frac{\partial H^{(R)}}{\partial y_{j}}(\mathbf{x}, \mathbf{y})=0 & j=1, \ldots, n
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1. Approximating critical points

- Solve the subsystem (A) to get an approximation of $(\mathbf{a}, \mathbf{b})$.
- Using the approximations, solve the subsystem ( $B$ )


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2. Monodromy

- Solve the subsystem $(A)$ to get an approximation of $(\mathbf{a}, \mathbf{b})$.
- Solve the subsystem $(B)$ using monodromy with $(\mathbf{x}, \mathbf{y}, t)=(\mathbf{a}, \mathbf{b}, 1)$.
- Caveat: the subsystem (B) may have several irreducible components. (Fail to find all critical points)


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## Experiments : Combinatorial examples

| Examples | square-root | Apéry ((2) | Apéry そ(3) | Random | 3D Walk |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Elapsed time (s) <br> ACSVHomotopy.jl | 0.01 | 0.025 | 0.7 | 0.9 | 0.08 |
| Maple implementation | 0.06 | 0.06 | 0.3 | 840 | 2.7 |

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| Elapsed time (s) Examples | square-root | Apéry 弓(2) | 2D Walk | GRZ | Random |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Polyhedral homotopy | 29.5 | 670 | INC | 236 | INC |
| Approximating Crits | 0.72 | 3.8 | 15.3 | 3.6 | 189.4 |
| Monodromy | 14.9 | 8.5 | 31.9 | 3.8 | 583.1 |

## Future directions

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$$

- Geometric understanding of ( $\star$ )
- What is degree for generic $H$ ?
- Numerical techniques for ( $\star$ )
- How to improve the performance of monodromy?
- Solving equation-by-equation (i.e. regeneration)
- How to verify the completeness?


## Thank you for your attention

The paper is available at
(https://arxiv.org/pdf/2208.04490.pdf)

